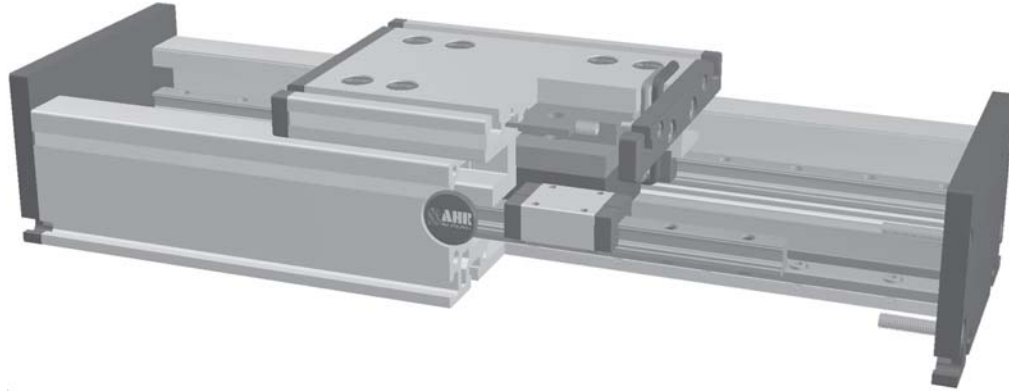


# Positioning system DSM 160, 200

Specifications

## Linear motor drive



### Function:

This unit consists of a rectangular aluminium profile with 2 integrated rail guidance. The linear-motor DSM unit is based on the principle of a linear, synchronous AC motor. The guiding profile is fitted with permanent magnets as stator (secondary part). The carriage is fitted with the actuator (primary part). The magnetic attraction causes a force between carriage and guiding profile also in the absence of current. This force can be used for the initial tension of the bearings. Several carriages (primary parts) can be driven independently on one guiding profile.

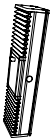
**Fitting position:** As required. Max. length 6.000 mm without joints.

**Carriage mounting:** By T-slots.

**Unit mounting:** By T-slots and mounting sets. The linear axis can be combined with any T-slot profile.

**Carriage support:** In the standard version, the carriage runs on 4 runner blocks which can be serviced at a central servicing position. For longer carriages the number of runner blocks can be increased. Repeatability ± 0,05mm mm. Repeated accuracy max. ± 0,05mm bis 4.000 mm, ± 0,1 >4.000 mm.

9.1

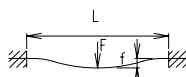


Forces and torques	Size	160			200		
	Motor size	1	2	3	1	2	3
	permitted dyn. Forces*	10000 km			10000 km		
	F <sub>a</sub> (N)	1200	1800	5500	3600	5500	11000
	F <sub>zm</sub> (N)	1590	2800	7030	4990	7640	13860
	F <sub>z</sub> (N)	1775	1775	3550	4092	4092	8184
	M <sub>x</sub> (Nm)	160	128	153	357	231	462
	M <sub>y</sub> (Nm)	373	351	532	769	556	1540
	M <sub>z</sub> (Nm)	222	261	328	585	654	906
Number of runner blocks	4	4	8	4	4	8	
<b>All forces and torques related to the following:</b>							
existing values $\frac{F_y}{F_{y_{dyn}}} + \frac{F_{zm}}{F_{zm_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1,5$ values of table							
<b>Motor specifications F<sub>x</sub></b>							
Motor size	1	2	3	1	2	3	
Carriage weight (kg)	4,8	5,3	7,1	10,9	11,4	16,9	
Weight primary part (kg)	1,4	3,7	5,2	4,5	6,4	8,4	
permanent (N)	115	271	406	383	574	766	
Max. (N) 1sec.	323	607	911	868	1301	1735	
<b>Moving force without current</b>							
N	30	30	60	40	40	80	
<b>Geometrical moments of inertia of aluminium profile</b>							
I <sub>x</sub> mm <sup>4</sup>	2,13 x 10 <sup>6</sup>			4,81 x 10 <sup>6</sup>			
I <sub>y</sub> mm <sup>4</sup>	12,3 x 10 <sup>6</sup>			26,0 x 10 <sup>6</sup>			
Elastic modulus N/mm <sup>2</sup>	70000			70000			

### Formula: DSM

Deflection:

$$f = \frac{F \cdot L^3}{E \cdot I \cdot 192}$$



f = deflection (mm)  
 F = load (N)  
 L = free length (mm)  
 E = elastic modulus 70000 (N/mm<sup>2</sup>)  
 I = second moment of area (mm<sup>4</sup>)

Nominal lifetime:

$$L = \left( \frac{C}{F} \right)^3 \times 10^5$$

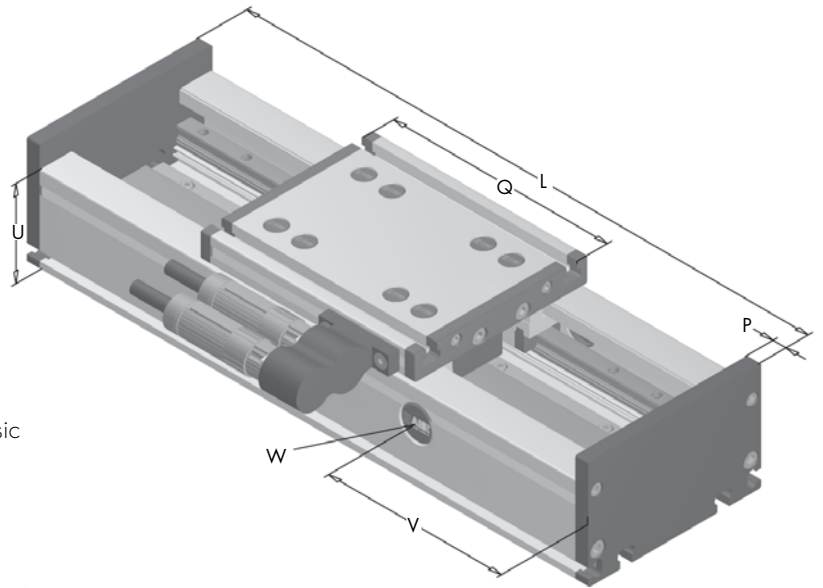
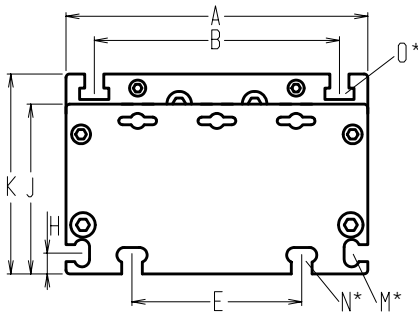
C = Dynamic load faktor (N)  
 F = Middle load (N)

\* referred to life-time



# Positioning system DSM 160, 200

Dimensions (mm)

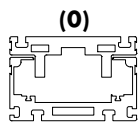


Increasing the carriage length will increase the basic length by the same amount.

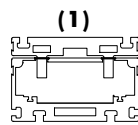
\*For slide-nuts refer to chapter 2.2 page 2  $V = Q + 100 \text{ mm}$   $W = \text{servicing position}$

Size □	Basic length L	A	B	E	H	J	K	M for	N for	O for	P	U	Basic weight Motor size 1/2/3	Weight per 100 mm Motor size 1/2/3
DSM 160	Q + 30	160	130	90	11	90	106	M 6	M 8	M 8	12	80	12,4/16,7/22,6 kg	1,7/2,0/2,0 kg
DSM 200	Q + 35	200	160	140	15	110	129	M 8	M 10	M 10	15	100	30,0 /33,0 /44,2kg	3,1/3,1/3,1 kg

**0 Choice of guide body profile:**



without internal profile and cover bands



without internal profile with cover bands (L max. 2000mm)



with bellows

Stainless version upon request.

**1 Measurement system**

- (1) Measurement system LE100 5V Resolution 0.05
- (2) Measurement system LE100 24V Resolution 0.05
- (3) Hall sensor
- (4) Measurement system provided by customer

**1 Plug**



**1 Motor size**

- (1) Motor size 1 with  $Q_1$
  - (2) Motor size 2 with  $Q_2$
  - (3) Motor size 3 with  $Q_3$
  - (4) Supply with  $Q_1^*$
  - (5) Supply with  $Q_2^*$
  - (6) Supply with  $Q_3^*$
- \* = provided by customer

Dimensioning criteria for motor output						
	$l_p \leq$	$b_p \leq$	$h_{ps} \leq$	$Q_1$	$Q_2$	$Q_3$
160	Q - 70	71	50	316	360	461
200	Q - 70	85	62	410	444	610

$l_p$  = length primary part;  $b_p$  = width primary part;  
 $h_{ps}$  = height primary part + height secondary part + interspaces primary-/secondary part

For standard carriage length see 'Q' in table. The carriages can be delivered in any non-standard length upon request; the longer the carriage, the greater the load capacity. Digital - controllers and linear - encoder refer to chapter 9.1 page 8.

**1500** Basic length + stroke = total length

DSM	160	0	0	1	1	0	0	1	01500
	Pos. 1	2	3	4	5	6	7		

Sample ordering code:

DSM160, Bahr Modultechnik Linear motor, standard body profile, Measurement system LE100 5V, Plug Pos. 1, motor size 1, 1154 mm stroke

