



# Scandrive AL Linear actuators

Servo actuators for register control



There are many exacting demands of engineering components in a modern printing press. The ability to produce a bright and sharp colour print at high speed is a matter of extreme precision in terms of positioning the print on the paper. Adjusting the sidelay and circumferential position of the plate cylinder to within 1/100th of a mm, despite the vibrations of the press, is a critical operation.

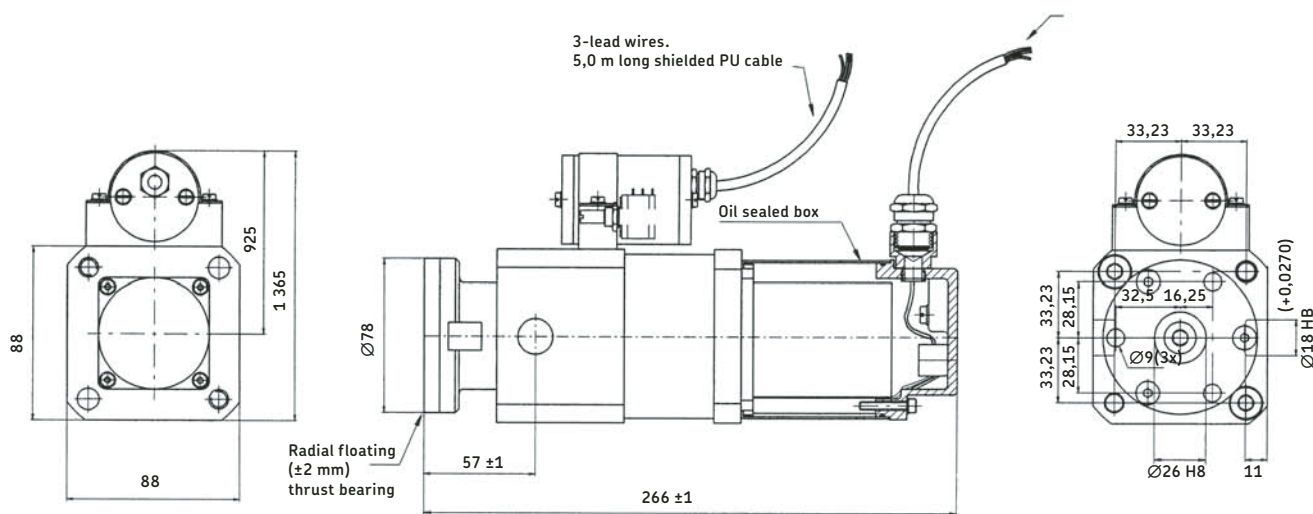
The SKF AL family of products is specifically designed and built for this purpose. High resolution, minimal backlash and high rigidity are the primary features.

Distinct mechanical end stops prevent jamming if accidentally run outside the range. As standard, the unit is supplied with a robust stepping motor built into a housing that shields it from oil, dust and EMC problems. Both synchronous or asynchronous AC-motors are available.

A potentiometer, or an inductive gauge, indicating the zero position, are available for positional feedback. SKF is specifically geared to creating customised solutions for register actuator problems. We have successfully dealt with any number of special requirements. Ask us. We know how!

#### Shell cylinder register system

For perfect registration on double-wide presses, fan-out poses a problem. SKF has developed a specific solution: 2 function actuators, one at each end of the plate cylinder, enable separate sidelay and circumferential adjustments to each of the two halves of the plate cylinder to be made. No more compromises needed to determining which pages shall have preference in terms of perfect register! Another window opened to achieve "zero error" production.



### Technical features

The thrust bearing connects to the plate cylinder shaft (sidelay register) or to a helical gear wheel (circumferential register). It floats radially within  $\pm 2$  mm in order to allow parallel adjustments of the plate cylinder position. The housing is mounted either flat on a console or by pivot pins. The pivot mounting allows for adjustments in inclination. The stepper motor responds to incremental movement commands with complete precision. One "half step" defines the minimum increment 0,00012 mm.

The stepper can also be programmed to work within a wide speed range, from 0 to approx 0,5 mm per second without changing any mechanical parts. If an AC-motor is used, the speed is normally determined by the AC supply frequency, be it 50 or 60 Hz. A gear motor with an additional gear ratio is used to provide the desired speed. For a wider range, an

inverter may be used. With the AC-motor, the incremental movement is determined by the period for which the motor is connected. Backlash, or "lost motion", when changing direction of motion, is critical for the sidelay register. The SKF AL is designed around a precision-cut trapezoidal screw running in a nut- and counter-nut design. These are pre-set at the factory, to eliminate all backlash. Over a period of many years, wear may cause a few 100ths of a mm backlash. If this should occur, the setting can be re-adjusted to zero in conjunction with a major overhaul.

The SKF AL unit comes as a ready-to-install unit that is fitted in virtually no time during final assembly. It is the natural answer to the modern logistic approach to the production of complex machinery: Purchase first, then have it delivered and installed "just-in-time".

### Examples of customized products



RGA (variant)  
Fluid media through centre.



AD (variant)  
Shell-cylinder system.  
Sidelay and circumference integrated.

| Technical data          | Unit | AL30P         | AL20P         | AL05P         | AL05IND   | RGA                |
|-------------------------|------|---------------|---------------|---------------|-----------|--------------------|
| Max thrust force        | N    | 27 000        | 20 000        | 5 000         | 5 000     | 20 000             |
| Thrust bearing capacity | C,N  | 25 000        | 25 000        | 25 000        | 25 000    | 80 000             |
| Thrust bearing capacity | CO,N | 65 000        | 65 000        | 65 000        | 65 000    | 199 000            |
| Mechanical stroke       | mm   | 6             | 6             | 17            | 12        | 8                  |
| Speed                   | mm/s | 0 to 0,15     | 0 to 0,15     | 0 to 0,5      | 0 to 0,5  | 0 to 13            |
| Feedback                | -    | Potentiometer | Potentiometer | Potentiometer | Inductive | Dual potentiometer |
| EMC shield              | -    | Yes           | Yes           | Yes           | Optional  | No                 |